

Camera Based Optical Wireless: A Visual MIMO approach to V2V communication

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1. MOTIVATION

- The inherent limitations in RF spectrum availability and susceptibility to interference make it difficult to meet the reliability required for vehicular safety applications
- Optical Wireless for V2V :
 - highly directional communication
 - limited range (10s of meters) limited power, high background noise
 - mechanically steering transmitter and/or receiver is very costly
 - single photodiode receiver may not work in such a mobile setting
- LEDs for rear and head-lights and Cameras (e.g. parking assistance, rear-view cameras) are getting common in cars



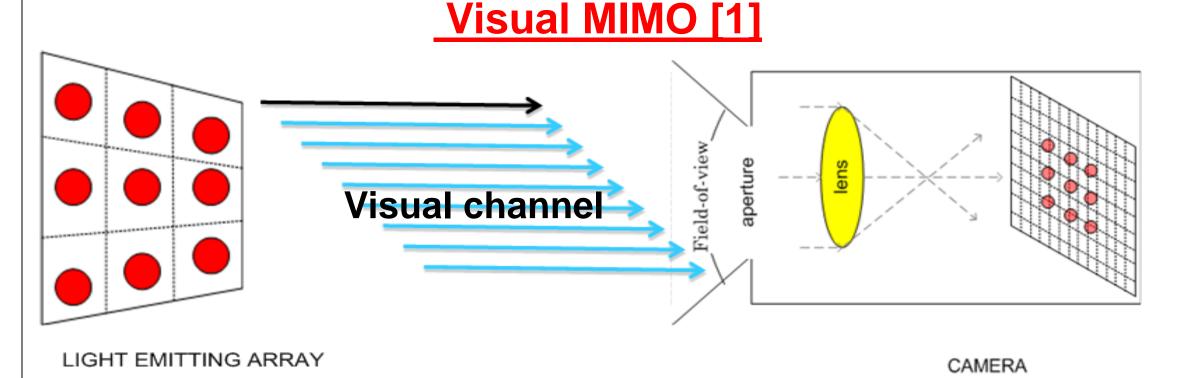
LED head-light

Why not use them for communication?

4. Visual MIMO V2V Demo [2]

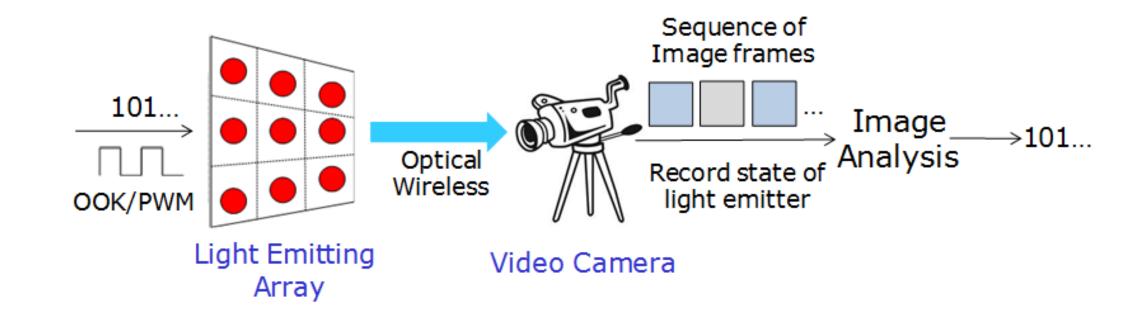


2. Light Emitting Array – Camera Communication



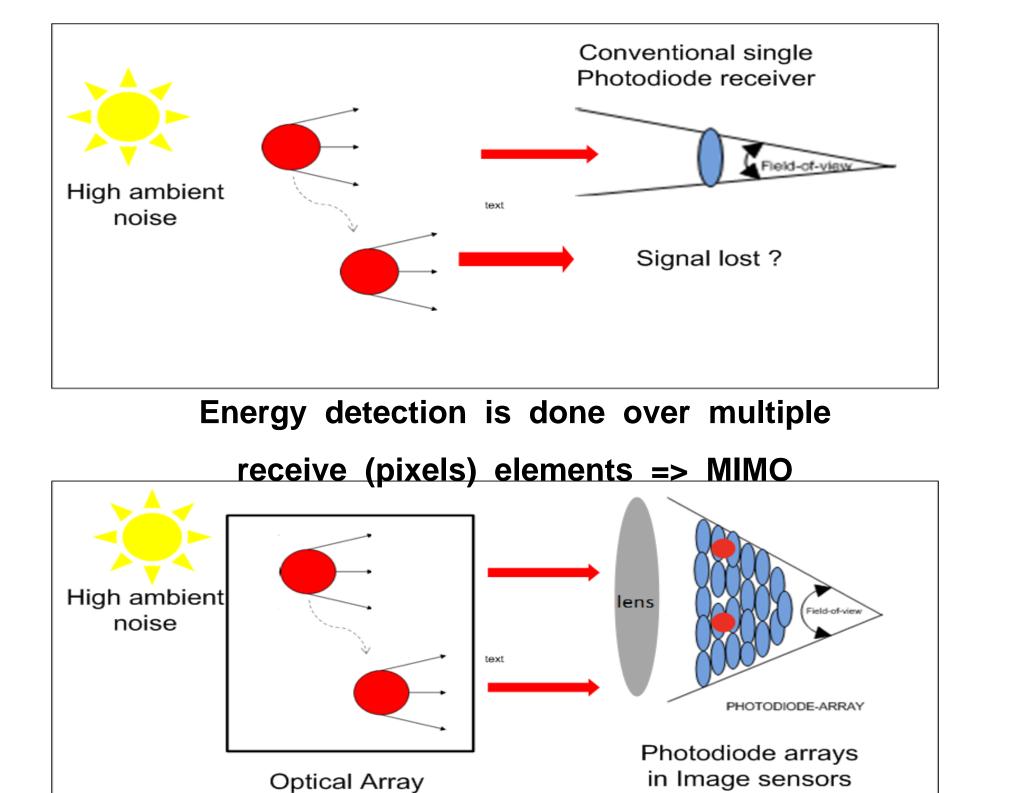
Optical Array transmitter + Camera receiver = VISUAL MIMO

How does it work?



What's new...

- Computer vision based image analysis techniques can be used to spatially separate signals and remove interferences from distracters such as traffic lights
- Conventional approaches use photodiode receivers [3] or complex hardware processing [4]



(cameras)

transmitter

3. Visual MIMO prototype for V2V data Tx by pressing a toy

- An LED array transmits the brake pedal intensity information (0-255) in the form of ON-OFF pulses(ON = bit 1, OFF = bit 0) when triggered by an user
- Retrieved data is displayed on a receiver computer screen as colors (not-pressed = green, half-pressed = yellow, fully pressed = red
- matching tracking Template algorithm implemented in OpenCV based on a binary template of the LED array

5. REFERENCES

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- 3. S. Kitano, S. Haruyama, and M. Nakagawa, Led Road Illumination Communications System, VTC, IEEE 58th, volume 5, pages 3346} U3350, Oct. 2003.
- 4. T. Saito, S. Haruyama, and M. Nakagawa, Inter-vehicle Communication and Ranging Method Using LED Rear-Lights, Proceedings of Conference on Communication Systems and Networks, 5:278{283, Aug 2006