WINLAB Research Overview March 2022



Rutgers, The State University of New Jersey <u>www.winlab.rutgers.edu</u> Contact: Prof. D. Raychaudhuri, Director <u>ray@winlab.rutgers.edu</u>

WINLAB at Rutgers University:

University-Industry Research Center Specializing in Wireless Technology

Founded in 1989



~25 Faculty & Staff ~45 PhD Students ~10 sponsor companies



WINLAB Tech Center Facility, North Brunswick, NJ

Center's research portfolio spans: information theory, radio technology, wireless systems, mobile networks and computing



Extensive experimental research infrastructure including ORBIT & GENI testbeds, SDR, ...



Low Power IoT device



SDR unit



Massive MIMO



ORBIT Radio Grid



GENI Cloud Rack

WINLAB Research Topics Map (~2020-22)



WINLAB System Research Themes

- □ Next-gen mobile/Internet FIA/5G/NGMN, ...
- Decentralized spectrum architecture (SII, SCM)
- □ Edge cloud for mobile real-time CPS services (AoI, distributed ML)
- □ Software defined wireless networks (O-RAN, O-NAP)
- □ Research testbeds: ORBIT, CloudLab, COSMOS, COSMIC
- Automotive infoverse, Cloud-assisted autonomous vehicles
- □ Smart Building, Smart City, ... (ERC collaboration with Columbia)
- Health IT systems and applications
- □ Resilient architecture; disaster recovery networks (NSF, NIST)

WINLAB Summary: People





Roy Yates

Dipankar Raychaudhuri





Lisa Musso

Narayan Mandayam

Waheed Bajwa



Yinying Chen



Predrag Spasojevic





Yanyong Zhang

?

Marco Gruteser

Ivan Seskar



Yicheng Lu



Vivek Singh



Noreen DeCarlo

Dick Frenkiel

Janice



Rich Howard



Richard Martin



Anand Sarwate

Thu Nguyen



Bo Yuan

~30-PhD & MS (see www.winlab.rutgers.edu for photos)



Campanella



Kolodziejski

Jakub



Elisa Servito



Prashanthi Madala

WINLAB Summary: Industry Sponsors & Partners (Current & Recent)



BBN Technologies

*Research Partners

Selected Research Projects

ORBIT Testbed: Massive-MIMO

Ivan Seskar,

32 USRP X310s

□ Available FPGA resources:

Resource Type	Number
DSP48 Blocks	58K
Block Rams (18 kB)	14K
Logic Cells	7.2M
Slices (LUTs)	1.5M

- RF 2 x UBX-160 (10 MHz 6 GHz RF, 160 MHz BB BW)
- 2 x 10G Ethernet for fronthaul/interconnect
- Four corner movable mini-racks (4 x 16 x 16 -> 1 x 64 x 64)
- > 500+ GPP Cores/CloudLab Rack
- Number of GPU platforms
- 32x40G SDN aggregation switch



Massive MIMO Measurements

Ivan Seskar,



Distributed Dynamic Spectrum (SMAP) Architecture

Prof. D. Raychaudhuri



SMAP Proof of Concept using ORBIT Testbed

Benchmark experiment setup for channel assignment algorithm





No cooperation between WD controllers: LTE BS1 causes interference to Wi-Fi AP3 when operating on the same channel Inter-network coordination between WDs: interference avoidance between LTE and Wi-Fi

SMAP Experimental Performance: Wi-Fi/LTE Coexistence

Fairness is achieved through Inter-Network Coordination







Throughput of Wi-Fi/LTE averaged over 5 experiment runs

Mobile Core Network: 5G vs 4G Latency

- 4G has high latency due to control plane signaling and radio framing
- 5G improvements include
 - □ Modular architecture (NFV)
 - Session setup and management improvements
- Further improvements will require
 - Self certifying packets (fast authentication)
 - ICN packet switched architecture with minimum signaling
 - □ "Flat" core network → no gateways, distributed mobility support at routers





Source: § J. Huang, et al., "A Close Examination of Performance and Power Characteristics of 4G LTE Networks", in ACM MobiSys 2012

Mobile Core Network: 4G LTE Connection Establishment



Mobile Core Network Based on NamedObject MF ArchitectureControl PlaneData Plane



- MobilityFirst (MF) is a Future Internet Architecture based on the concept of:
 - Unique names associated with Internet-connected objects
 - Distributed hash-map based database for mapping names to addresses
- No GTPs in control plane
- Distributed forwarding in data plane

Mobile Core Network: Simplified MF-based Protocol Stack



- 1. LTE RAN remains unchanged
- 2. Simplified end-to-end protocols for MobilityFirst

Mobile Core Network: Proof-of-Concept 5G Core Prototype

- MF (MobilityFirst)/ICN hoststack and Click router updated to work with OAI
- OAI modified to remove gateways and tunneling
- Preliminary ORBIT experiments on low latency



Mobile Core Network: Latency Comparison with Commercial Network

- UE attachment latency (MAC + network)
- Distributed core experiment on ORBIT
 - 50 runs of UE wakeup (i.e. control + data plane latencies)
- Commercial ISP data from MobileInsight*
 - 780 crowd-sourced smartphone logs from 2016



Source: Shreyasee Mukherjee, PhD thesis 2018, WINLAB

- Average control messaging latency:
 - Distributed core: 49 msec
 - Commercial ISP: 181 msec

Edge Cloud: Multi-tier Architecture

- Cloud service latency significant component of E2E
- Bringing the cloud closer to the edge helps:
 - □ Lower network RTT
 - NFV placement
- Several design challenges with edge cloud:
 - Dynamic assignment, load balancing
 - Mobility support
 - Real-time orchestration
 - Virtual network slicing



Edge Cloud: City Scale Evaluation Model



Chicago Wi-Fi AP Locations (~1.1K)

ſ	Parameter	Value 5.18 km ²			
ł	Area				
Ì	Number of APs	1.1K			
Ì	Number of Users	55K			
Ì	Distribution of Users	Random			
	Bandwidth (Uplink)	27, 150 and 300 Mbps 54, 300 and 600 Mbps 1500 Bytes 5 Machines 2			
ĺ	Bandwidth (downlink)				
	Packet Size				
	Edge Resources (baseline)				
[α				
	β	1			
[γ	0.1			
	δ	1			
[ρ	0.9			
[\overline{w}	0.5			
ſ	n	10			



Edge Cloud: Sample Results for Hybrid MEC Evaluation



Edge provides significant performance improvement

Fast front-haul network needed to enable the edge...

Distributed ML over Edge Clouds: System Architecture





Distributed ML over Edge Clouds: Mobile Offload Performance Profiling

- mobile device: Jetson Tx2; edge device: 1080Ti
- Iink: 200Mbps
- network: VGG19

Layer (type)	Output Shape	Parameters#	Size (KB)	MFLOPS	Cloud Proc (ms)	Mobile Proc (ms)	Trans (ms)	Total (ms)
Original Image	(224, 224, 3)	0	173	0	3.713	0	6.92	10.633
$\operatorname{conv1}_1 + relu1_1$	(224, 224, 64)	1792	12544	173	3.627	0.427	501.76	505.814
$\operatorname{conv1}_2 + relu1_2$	(224, 224, 64)	36928	12544	3699	3.362	1.743	501.76	506.865
pool1	(112, 112, 64)	0	3136	2.4	3.289	2.106	125.44	130.835
$conv2_1 + relu2_1$	(112, 112, 128)	73856	6272	1850	3.158	2.757	250.88	256.795
$\operatorname{conv2}_2 + relu2_2$	(112, 112, 128)	147584	6272	3699	2.953	3.775	250.88	257.608
pool2	(56, 56, 128)	0	1568	1.2	2.910	3.988	62.72	69.618
$conv3_1 + relu3_1$	(56, 56, 256)	295168	3136	1850	2.774	4.664	125.44	132.878
$conv3_2 + relu3_2$	(56, 56, 256)	590080	3136	3699	2.561	5.722	125.44	133.723
$conv3_3 + relu3_3$	(56, 56, 256)	590080	3136	3699	2.345	6.794	125.44	134.579
pool3	(28, 28, 256)	0	784	0.6	2.310	6.968	31.36	40.638
$conv4_1 + relu4_1$	(28, 28, 512)	1180160	1568	1850	2.145	7.788	62.72	72.653
$conv4_2 + relu4_2$	(28, 28, 512)	2359808	1568	3699	1.874	9.134	62.72	73.728
$conv4_3 + relu4_3$	(28, 28, 512)	2359808	1568	3699	1.604	10.475	62.72	74.799
pool4	(14, 14, 512)	0	392	0.3	1.558	10.703	15.68	27.941
$conv5_1 + relu5_1$	(14, 14, 512)	2359808	392	925	1.451	11.235	15.68	28.366
$conv5_2 + relu5_2$	(14, 14, 512)	2359808	392	925	1.346	11.756	15.68	28.782
$conv5_3 + relu5_3$	(14, 14, 512)	2359808	392	925	1.239	12.288	15.68	29.207
pool5	(7, 7, 512)	0	98	0.075	1.203	12.466	3.92	17.589
fc6 + relu6	(1, 1, 4096)	102764544	16	206	0.239	17.254	0.64	18.133
fc7 + relu7	(1, 1, 4096)	16781312	16	34	0.060	18.143	0.64	18.843
fc8	(1, 1, 1000)	4097000	3.9	8	0	18.441	0.156	18.441
total		138357544	540459					

Distributed ML over Edge Clouds: Data Parallelism for Faster Inference

 target applications: multi-object detection / multi-face recognition





3

(a) image with equal partitioning

(b) image with ideal partitioning

run video frame partitioning for data parallelism





Accuracy and processing time with different frame partitioning schemes

Mobile Edge Cloud: Vehicular Applications

Cloud Assisted Driving and Self-Driving will soon become feasible due to advances in wireless network ("5G") and edge cloud technology



Mobile Edge Cloud: Collaborative Sensing for Autonomous Driving

Prof. Marco Gruteser

- Explore how vehicles can collaboratively sense their surroundings and gathering accurate vehicle counts and speed estimates from in-vehicle camera footage
- Developed speed estimation techniques from in-car camera video
- Applied to traffic monitoring application, which computes congestion level using vehicle counts and speeds

- We have developed a vehicle-based camera sensing platform and use a deep-learning system (YOLO*) for image detection.
- Our preliminary vehicle count accuracy is about 80% and we are in the process of refining the algorithms.
 - * http://pjreddie.com/darknet/yolo





COSMOS Testbed

COSMOS: Project Vision

- Next-gen mobile expected to migrate from today's smartphones to real-time interaction with the physical world
- Application domains include AR, VR, connected car, smart city (with highbandwidth sensing), industrial IoT, ...
- Requires ultra high BW and low latency tightly coupled with edge computing

Augmented Reality



Smart City + Connected Car





Industrial Control

COSMOS: System Architecture

- COSMOS architecture has been developed to realize ultrahigh BW, low latency and tightly coupled edge computing
- Key design challenge: Gbps performance + full programmability at the radio level
- Developed a fully programmable multi-layered (i.e. radio, network and cloud) system architecture for flexible experimentation



COSMOS is an open, programmable platform suitable for More information at: <u>www.cosmos-lab.org</u>evaluation and testing of 5G designs and applications

COSMOS: System Implementation

- System design based on three levels of SDR radio node (S,M,L); incl mmWave
- All-optical SDN x-haul with high BW, low latency WDM switching
- Edge clouds co-located with M,L base stations
- NYC deployment with connectivity through 32 AoA PoP





COSMOS Network Operations Center (@Rutgers)

COSMOS Deployment in NYC/Uptown Manhattan (@West Harlem)

COSMOS: NYC Deployment

Phased deployment plan: Pilot, Phase 1, ... Phase 2



COSMOS: Smart Intersection Experiment

COSMOS Edge Cloud infrastructure deployed at 120St and Amsterdam ... being used for ongoing smart intersection experiment

